

Research Group

Data Mining and Machine Learning

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6 working groups

Database Techniques for Data Mining



Christian Böhm

Machine Learning with Graphs



Nils Kriege

Data Mining



Claudia Plant

Natural Language Processing



Benjamin Roth

Probabilistic and Interactive Machine Learning



Sebastian Tschiatschek

Scalable Algorithms for Graph Mining



Yllka Velaj

3 key research "directions"

- **Reinforcement Learning**
 - Reward / constraint inference
 - Exploration & abstraction
- **Interactive machine learning**
- Probabilistic (Generative) Models

The group



Motivation

[C. Morrison et al., CHI'21]





Intelligent agents enabling
efficient & seamless collaboration

Challenge: Collaboration in the face of

- (significant) mismatch in inputs,
- (initially) non-aligned goals and constraints,
- (complex) large state spaces

Key goals and challenges



Intelligent agents enabling
efficient & seamless collaboration

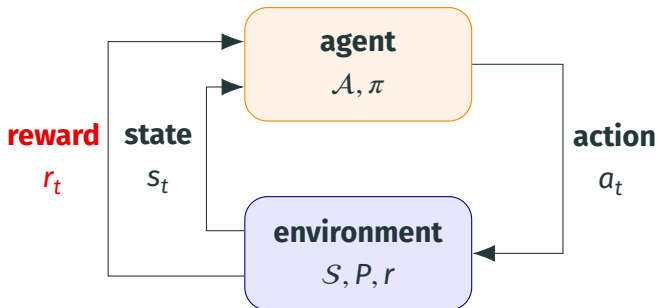
Challenge: Collaboration in the face of

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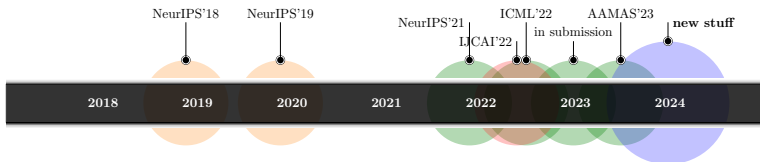


Teaching and learning
desired and undesired behavior

Reinforcement learning in a nutshell

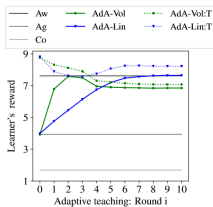


Past and future work



Teaching and learning under mismatch

- Reward linear in expert's features: $r.s/ = \langle \phi^E, w_i \rangle$
- *NeurIPS'18*: Learner's ϕ^L and expert's features ϕ^E differ
- *NeurIPS'19*: Constraints/prefs. on feature expectations

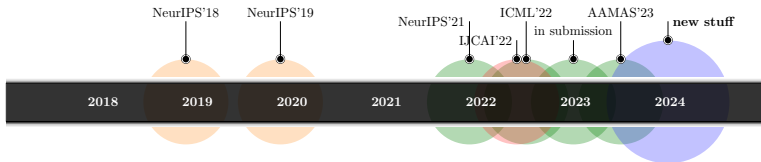


(a) Reward over teaching rounds

Teacher	Env		
	10 × 10	15 × 15	20 × 20
AWARE-CMDP	7.62 ± 0.02	7.44 ± 0.04	7.19 ± 0.04
AGNOSTIC	3.94 ± 0.09	3.84 ± 0.06	3.95 ± 0.06
CONSERV	1.68 ± 0.01	1.67 ± 0.012	1.62 ± 0.02
ADAWARE-VOL (3 rd)	7.50 ± 0.14	7.50 ± 0.04	7.29 ± 0.05
ADAWARE-VOL (end)	6.85 ± 0.33	7.06 ± 0.06	6.77 ± 0.08
ADAWARE-LIN (3 rd)	6.14 ± 0.08	6.28 ± 0.10	6.37 ± 0.08
ADAWARE-LIN (end)	7.64 ± 0.02	7.53 ± 0.03	7.29 ± 0.06

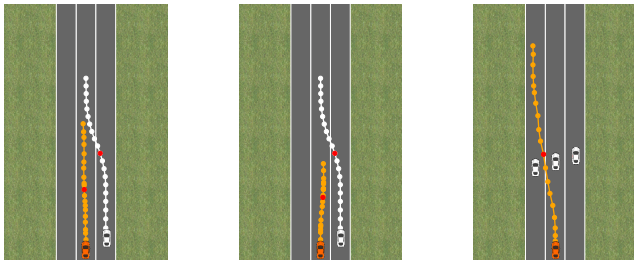
(b) Varying grid-size

Past and future work

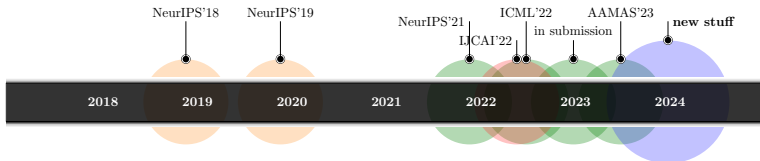


Effectively learning about rewards & constraints

- *NeurIPS'21/ICML'22/AAMAS'23/in submission*: Different FB types / constraints / information directed learning



Past and future work



Understanding large state spaces

- IJCAI'22 / ongoing: Abstractions of large state spaces

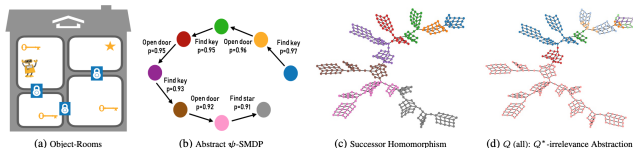
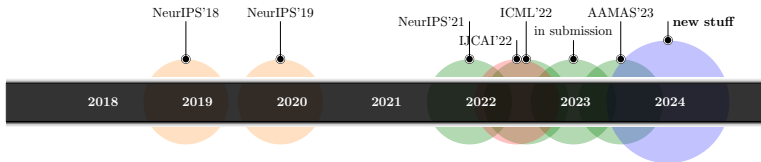


Figure 1: MDP abstraction in the Object-Rooms domain. (b) Abstract ψ -SMDP induced by our successor homomorphism from the ground MDP as shown in (c), the abstract states in (b) correspond to aggregated ground states of the same colour in (c). (d) Abstraction induced by approximate Q^* -irrelevance abstraction (cf. Appendix A.4) for *find key*; the abstraction does not carry temporal semantics, and is not reusable for other tasks e.g., *find star*. Another example can be found in Figure 10 in Appendix A.6 and more details are in the experiments section.

Past and future work



What's next/ongoing—collaborations welcome

- Active **3rd person imitation learning**
- Deeper understanding about learning from **stop-feedback**
- **Abstractions** for efficient exploration
- **Policy design** for continual reinforcement learning



[Photo credit: vog.photo]

References

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- Sebastian Tschiatschek, Ahana Gosh, Luis Haug, Rati Devidze, Adish Singla, *Learner-aware Teaching: Inverse Reinforcement Learning with Preferences and Constraints*, NeurIPS'19
- Cecily Morrison, Edward Cutrell, Martin Grayson, Anja Thieme, Alex Taylor, Geert Roumen, Camilla Longden, Sebastian Tschiatschek, Rita Faia Marques, Abigail Sellen, *Social Sensemaking with AI: Designing an Open-ended AI experience with a Blind Child*, CHI'21
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